Networking on WARP

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Today's Agenda

- Outstanding questions?
- Networking on WARP lecture
- Labs 4, 5, and 6
- Workshop wrap-up



Physical Layer Basics



Network Layer Basics



Network Layer Basics



Network Layer Basics



Targeting WARP Hardware

(Understanding the Development Environment)



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(Understanding the Development Environment)











Our Focus: Medium Access Control



- All commercial 802.11 chipsets are closed
- Many opportunities for cross-layer research

Outline

- Overview of Medium Access Control
- Design Realization
- Example
- Lab Exercises

Medium Access Control Overview







User 3









Received a jumbled packet... infer a packet collision



Received a jumbled packet... infer a packet collision

User 5

User 4

User

Data

Data

What if we ACK every transmit, and retransmit when we receive no ACK?











6







Random Backoffs

• **PROBLEM:**

Retransmissions can collide *ad infinitum!*

• **SOLUTION:** Wait a random amount of time before a retransmit



Contention Window increases over time

Important Extensions

- Carrier Sense Multiple Access (CSMA)
 - Listen to the medium before sending
- Request to Send / Clear to Send (RTS/CTS)
 - "Reserve" the medium with a short packet before sending a long one



- Program high-level MAC behavior independent of hardware
- Use the WARPMAC
 framework to
 stitch the MAC to
 hardware



 No way to "lock" the framework and have it support all possible future MAC layers



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Solution: WARPMAC must grow with new algorithms



 No way to "lock" the framework and have it support all possible future MAC layers

Solution: WARPMAC must grow with new algorithms Problem: How do we maintain sync between designs?
• Snapshots of the WARP repository

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- Free, open-source releases at regular intervals
 - Today's exercises are on nearly-released Reference Design v12
 - Keeps pace with Xilinx design tools

- Snapshots of the WARP repository
- Free, open-source releases at regular intervals
 - Today's exercises are on nearly-released Reference Design v12
 - Keeps pace with Xilinx design tools
- Reference design is an example of:
 - a working PHY
 - a working MAC
 - the way all the pieces fit together



Xilinx Peripherals

WARPMAC

WARPPHY

WARPMAC

WARPPHY

WARPMAC

WARPPHY

PHY Driver:

- Configure very low-level parameters
 - Correlation thresholds
 - FFT scaling parameters
 - Filter coefficients
 - Etc.

User Code WARPMAC WARPPHY



WARPMAC

WARPPHY

WARPMAC

WARPPHY

Radio Controller Driver:

- Set center frequency
- Switch from Rx to Tx mode and vice versa

User Code

WARPMAC

WARPPHY

WARPMAC

WARPPHY

WARPMAC

WARPPHY

PHY Control:

- Provides control over PHY commonalities
 - General initialization command
 - Configure constellation order
 - "Start" and "Stop" the PHY



WARPMAC

WARPPHY

WARPMAC

WARPPHY

Mostly PHY agnostic

User Code WARPMAC

WARPPHY

Drivers

Completely PHY dependent

WARPMAC

WARPPHY

MAC Control:

- Provides control over MAC commonalities
 - Timers for timeouts, backoffs, etc.
 - Carrier-sensing functions
 - Register user callbacks to ISRs
 - Etc.

User Code

WARPMAC

WARPPHY

WARPMAC

WARPPHY

WARPMAC

WARPPHY

User-level MAC Algorithms:

- High-level MAC algorithms
- Some examples so far:
 - Aloha
 - Carrier-sensing MAC
 - Opportunistic Auto-Rate (OAR)
 - MAC Workshop Exercises



WARPMAC

WARPPHY

An example: CSMA

- Carrier-sensing Multiple Access
- Serves as a foundation for a large class of other random access protocols
- Fairly simple algorithm







Transmit States



Transmit States

emacRx_int_handler

- Starts DMA transfer from EMAC to PHY

emacRx_callback

- Constructs Macframe header for data packet
- If medium is idle {

warpmac_prepPhyForXmit

- Configures PHY
- Copies Macframe header into PHY's buffer

warpmac_startPhyXmit

- Disables packet detection
- Starts radio controller's transmit state machine

warpmac_finishPhyXmit

- Polls PHY and waits for it to complete
- Enables packet detection and radio reception
- Starts a timeout timer

If medium is busy {

- Starts a backoff timer

- Clears EMAC and interrupt controller









Receive States

phyRx_goodHeader_int_handler

- Copies header into Macframe

phyRx_goodHeader_callback

- Checks address/type fields of Macframe header

If data {

- Constructs an ACK Macframe to prepare for a complete Rx packet

warpmac_prepPhyForXmit

- Configures PHY
- Copies Macframe header into PHY's buffer

- Polls PHY receiver and waits for a "Good" or "Bad" state If Good {

warpmac_startPhyXmit

- Disables packet detection
- Starts radio controller's transmit state machine

warpmac_prepEmacForXmit

- Starts DMA transfer from PHY to EMAC

warpmac_finishPhyXmit

- Polls PHY and waits for it to complete
- Enables packet detection and radio reception

warpmac_startEmacXmit

- Polls DMA and waits for it to complete
- Starts EMAC transmission

If acknowledgment {

}

- Clears timeout timer

- Clears interrupts in PHY and interrupt controller



Receive States

pł	<pre>nyRx_goodHeader_int_handler - Copies header into Macframe</pre>	
	phyRx_goodHeader_callback - Checks address/type fields of Macframe header If data { - Constructs an ACK Macframe to prepare for a complete Rx packet warpmac_prepPhyForXmit - Configures PHY	
	- Copies Machanie Reader Into PHY's builer - Polls PHY receiver and waits for a "Good" or "Bad" state If Good {	Fast Turn-Around Time
	warpmac_startPhyXmit Disables packet detection Starts radio controller's transmit state machine 	(TAT)
	warpmac_prepEmacForXmit - Starts DMA transfer from PHY to EMAC	
	warpmac_finishPhyXmit - Polls PHY and waits for it to complete - Enables packet detection and radio reception	User-Code
	warpmac_startEmacXmit - Polls DMA and waits for it to complete - Starts EMAC transmission	
	<pre>} } If acknowledgment { - Clears timeout timer }</pre>	
	- Clears interrupts in PHY and interrupt controller	






Timer States

timer_int_nandier	timer_	int_	hand	ler
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timer_callback

- Checks timer type

If timeout {

- Increments retransmission counter
- If maximum retransmissions reached, returns
- If not, starts a backoff timer

If backoff {

warpmac_prepPhyForXmit

- Configures PHY
- Copies Macframe header into PHY's buffer

warpmac_startPhyXmit

- Disables packet detection
- Starts radio controller's transmit state machine

warpmac_finishPhyXmit

- Polls PHY and waits for it to complete
- Enables packet detection and radio reception
- Starts a timeout timer

- Clears interrupts in timer and interrupt controller





All the preceding pseudocode translates naturally to the C-code in the Reference Design:

http://warp.rice.edu/trac/browser/ResearchApps/

MAC/CSMAMAC/csmaMac.c

 Set TIMEOUT Timer
 Transmit ACK via PHY
 Clear TIMEOUT
 Increment Resend Counter
 Set BACKOFF Timer
 Drop Packet

 Transmit States
 Deliver Packet to Sink
 Transmit DATA via PHY
 Transmit DATA via PHY
 Transmit DATA via PHY
 Set TIMEOUT
 Set TIMEOUT
 Set TIMEOUT

WARPMAC Structs

Macframe: phyHeader header /* Another struct */ unsigned char isNew /* Flag for new packets */

Fully documented in API (http://warp.rice.edu/WARP_API)

WARPMAC Structs

phyHeader:

unsigned char fullRate; /* Payload modulation rate */ unsigned char codeRate; /* Coding rate */ unsigned short int length; /* Payload length */ unsigned char pktType; /* Packet type */ unsigned char destAddr[6]; /* Destination address */ unsigned char srcAddr[6]; /* Source address */ unsigned char currReSend; /* Re-send count */ unsigned char reserved I; /* Unused */ unsigned char reserved2; /* Unused */ unsigned char reserved3; /* Unused */ unsigned short int checksum; /* CRC placeholder */

Fully documented in API (http://warp.rice.edu/WARP_API)



Lab Exercises

- Lab 4 noMAC: Too simple to be a MAC
- Lab 5 halfMAC: Receive-half of a MAC
- Lab 6 hopMAC: Channel-hopping extension



To test your noMac code, ping 10.0.0.20

Questions?

Remember to use the API: http://warp.rice.edu/WARP_API



halfMac



halfMac



Most Significant Bit (MSB)

Least Significant Bit (LSB)

Questions?

Remember to use the API: http://warp.rice.edu/WARP_API

hopMac





Questions?

Remember to use the API: http://warp.rice.edu/WARP_API

Logistics

- Contacting us
 - Support & technical questions
 - <u>http://warp.rice.edu/forums/</u>
 - Hardware sales
 - Mango Communications (<u>http://mangocomm.com/</u>)